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ADRIAN PERRIG & TORSTEN HOEFLE

Networks and Operating Systems (252-0062-00)

Chapter 9: I/O Subsystems

52131 Issue with opening Class 377 doors on the Thameslink route

Never underestimate the KISS principle!

February 2014 in The Observer

Concerns have been raised about increased faults when opening the doors of the Class 377 units at certain stations on the Thameslink route.

The incident that occurred took place on the Class 377 at the station, the Train Management System (TMS) indicates that the doors could be opened, preventing the doors from opening. This situation of the train from moving is a problem for the TMS, although the doors to open. In some instances, more than one door has failed to open, and this has caused the train to be delayed. The cause in several of the incidents, leaving passengers on the train without air.

It is noted that this has happened at many stations on the Brighton to Bedford route, but occurs most frequently at St. Pancras International, City Thameslink, Farringham, Bedford and Brighton. There are concerns that this could be an emergency exit if a incident were to occur, leaving passengers at risk.

It is noted that the doors have already been done with through fault to trigger the TMS of the doors, and this may also cause a problem in the number of doors that the doors do not receive the line.

However, we are aware that there are still occasional problems, which results in the driver having to enter manually the train where it is on the tracks not to be open in the TMS, or in the event of a fault, not working, using the emergency door release system in the train management system.

Local investigations are pointing towards the signal from the location being obtained by an unknown source.

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Thanks for the feedback! ☺

- Some answers:
 - Apologies for forgetting yesterday's book chapter! *Anderson/Dahlin: Chapter 13 ("Files and Directories")*
 - What do I need to know for the exam? *Everything that's mentioned on slides+exercises is essential. You should make sure you understand the concepts. This may require listening ☺. Everything else and the stories I tell are optional.*
 - Why are your slides not self-contained? *Believe me, it's better for you (cf. Rebecca Schumann "Digital Slideshows are the scourge of education").*

Algorithm for resolving open questions

(1) read book chapter, (2) ask friends, (3) ask TAs, (4) ask me

- I talked to the assistants to improve exercises
- I hope that works --- they're open for additional feedback!

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Metadata files

- File system metadata in NTFS is held *in files!*

File num.	Name	Description
0	\$MFT	Master file table
1	\$MFTir	Copy of first 4 MFT entries
2	\$LogFile	Transaction log of FS changes
3	\$Volume	Volume information & metadata
4	\$AttrDef	Table mapping numeric IDs to attributes
5	.	Root directory
6	\$Bitmap	Free space bitmap
7	\$Boot	Volume boot record
8	\$BadClus	Bad cluster map
9	\$Secure	Access control list database
10	\$UpCase	Filename mappings to DOS
11	\$Extend	Extra file system attributes (e.g. quota)

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Question: Huh? Where is it then?
 Answer: First sector of volume points to first block of MFT

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Our Small Quiz

- True or false (raise hand)
 - Directories can never contain cycles
 - Access control lists scale to large numbers of principals
 - Capabilities are stored with the principals and revocation can be complex
 - POSIX (Unix) access control is scalable to large numbers of files
 - Named pipes are just (special) files in Unix
 - Memory mapping improves sequential file access
 - Accessing different files on disk can have different speeds
 - The FAT filesystem enables fast random access
 - FFS enables fast random access for small files
 - The minimum storage for a file in FFS is 8kB (4kB inode + block)
 - Block groups in FFS are used to simplify the implementation
 - Multiple hard links in FFS are stored in the same inode
 - NTFS stores files that are contiguous on disk more efficiently than FFS
 - The volume information in NTFS is a file in NTFS

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In-memory data structures

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Opening a file

- Directories translated into kernel data structures on demand:

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Reading and writing

- Per-process open file table → index into...
- System open file table → cache of inodes

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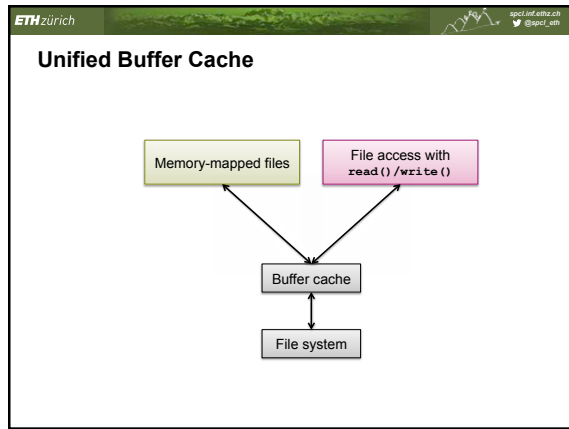
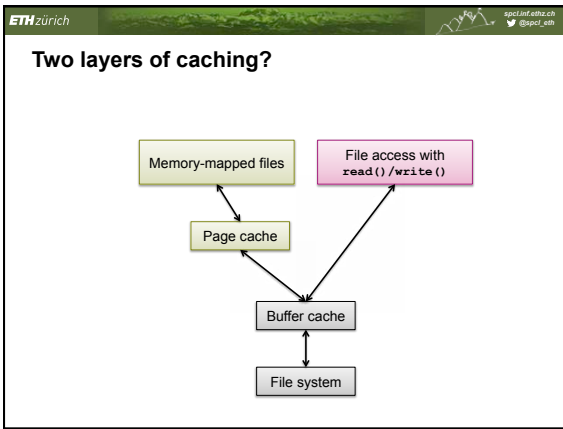
Efficiency and Performance

- **Efficiency dependent on:**
 - disk allocation and directory algorithms
 - types of data kept in file's directory entry
- **Performance**
 - disk cache – separate section of main memory for frequently used blocks
 - free-behind and read-ahead – techniques to optimize sequential access
 - improve PC performance by dedicating section of memory as virtual disk, or RAM disk

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Page Cache

- A page cache caches pages rather than disk blocks using virtual memory techniques
- Memory-mapped I/O uses a page cache
- Routine I/O through the file system uses the buffer (disk) cache
- This leads to the following figure



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Filesystem Recovery

- Consistency checking – compares data in directory structure with data blocks on disk, and tries to fix inconsistencies
- Use system programs to back up data from disk to another storage device (floppy disk, magnetic tape, other magnetic disk, optical)
- Recover lost file or disk by restoring data from backup

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Disks, Partitions and Logical Volumes

Partitions

0 Logical block address (LBA) on a single disk

- Multiplex single disk among >1 file systems
- Contiguous block ranges per FS

Logical volumes

Single *logical* volume with file system A

- Emulate 1 virtual disk from >1 physical ones
- Single file system spanning >1 disk

Multiple file systems

- How to name files in multiple file systems?
- Top-level volume names:
 - Windows A:, B:, C:, D:, etc. (problematic)
 - fs-systems.ethz.ch
- Bind "mount points" in name space
 - Unix, etc. (flexible)

Mount points

```

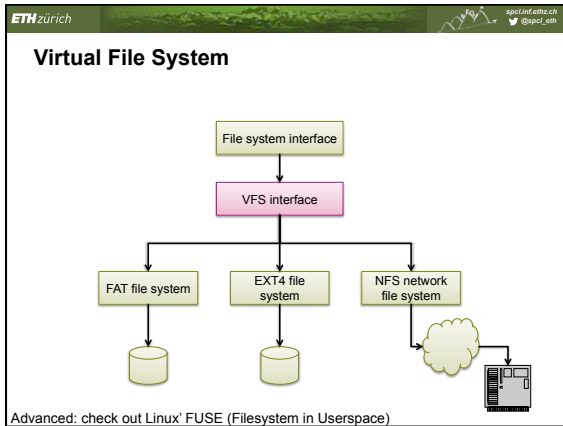
htor@rosal03:~$ df -h
Filesystem      Size  Used Avail Use% Mounted on
/dev/sda5       675G  420 599G   7% /
devtmpfs        64G   0    64G   1% /dev
tmpfs           64G   0    64G   0% /dev/shm
/dev/sda3       31G  1.9G  27G   7% /tmp
/dev/sda2       61G  819M  57G   2% /var
/dev/users      59T  4.7T  54T   8% /users
/dev/scratch    524T  67T  457T  13% /scratch/tencia
/dev/apps       30T  3.6T  26T  13% /apps
/dev/project    1.9P  1.2P  736T  62% /project
62@gn1:/scratch
htor@rosal03:~$
    
```

File hierarchy with mounts

Mount point (orange box)
Normal directory (green box)

Virtual File Systems

- Virtual File Systems (VFS) provide an object-oriented way of implementing file systems.
- VFS allows the same system call interface (the API) to be used for different types of file systems.
- The API is to the VFS interface, rather than any specific type of file system.



- ### Rest of today: I/O
1. Recap: what devices look like
 2. Device drivers
 3. The I/O subsystem

Recap from CASP:
What does a device look like?

- ### Recap: What is a device?
- Specifically, to an OS programmer:
- Piece of hardware visible from software
 - Occupies some location on a **bus**
 - Set of **registers**
 - Memory mapped or I/O space
 - Source of **interrupts**
 - May initiate **Direct Memory Access** transfers

Recap: Registers

- Details of registers given in chip "datasheets" or "data books"
- Information is rarely trusted by OS programmers ☹

8.4 LINE STATUS REGISTER
This register provides status information to the CPU concerning the data transfer. Table 8 shows the contents of the Line Status Register. Details on each bit follow.

Bit 0: This bit is the receiver Data Ready (RD) indicator. Bit 0 is set to a logic 1 whenever a complete incoming character has been received and transferred into the Receiver Buffer Register or the FIFO. Bit 0 is reset to a logic 0 by reading all of the data in the Receiver Buffer Register or the FIFO.

Bit 1: This bit is the Overrun Error (OE) indicator. Bit 1 indicates that data in the Receiver Buffer Register was not read by the CPU before the next character was transferred into the Receiver Buffer Register, thereby destroying the previous character. The OE indicator is set to a logic 1 upon detection of an overrun condition and reset whenever the CPU reads the contents of the Line Status Register. If the FIFO mode data continues to fill the FIFO beyond the trigger level, an overrun error will occur only after the FIFO is full and the next character has been completely received in the shift register. OE is indicated to the CPU as soon as it happens. The character in the shift register is overwritten, but it is not transferred to the FIFO.

Bit 2: This bit is the Parity Error (PE) indicator. Bit 2 indicates that the received data character does not have the

From the data sheet for the PC16550 UART (standard PC serial port) →

Registers

- Slightly more readable version:
- From Barrelfish, in a language called "Mackerel"
- Compiler generates code to do the "bit-banging"

```

register wr rw addr ( base, 0x0 ) "Mode control" {
  dir 1 "Data transfer: r/w/bs"
  rts 1 "Request to send?"
  out 0 "Out?"
  lsr 1 "Loop?"
};

register lr rw addr ( base, 0x7 ) "Line status" {
  dr 1 "Data ready?"
  oe 1 "Overrun error?"
  pe 1 "Parity error?"
  fe 1 "Framing error?"
  bi 1 "Break interrupt?"
  txf 1 "Transmitter holding register?"
  txst 1 "Transmitter empty?"
  rxfifo 1 "Error in RX FIFO?"
};

register wr rw addr ( base, 0x8 ) "Mode status" {
  dclr 1 "Data clear to send?"
  
```

Using registers

- From the Barrefish console driver
 - Very simple!
- Note the issues:
 - Polling loop on send
 - Polling loop on receive
 - Only a good idea for debug
 - CPU must write all the data not much in this case

```

int send_serial_register(int c)
{
    // Wait until FIFO can hold more characters
    while(PC20959_UART_LSR_REGISTER & LSR_TX_EMPTY == 0)
        ; // do nothing
    PC20959_UART_DR_REGISTER = c;
}

void serial_writechar(char c, int i)
{
    for (int i = 0; i < len; i++) {
        // This really belongs in a user-space terminal library
        if (i % 16 == 0)
            serial_writechar(c, i);
    }
}

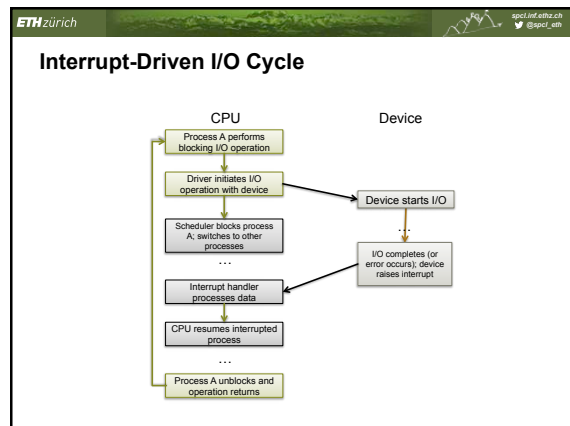
void serial_write(char *s)
{
    // Read as many characters as possible from FIFO
    while(PC20959_UART_LSR_REGISTER & LSR_RX_EMPTY == 0)
        char = PC20959_UART_DR_REGISTER;
    serial_readchar(s);
}
    
```

Very simple UART driver

- Actually, far too simple!
 - But this is how the first version always looks...
- No initialization code, no error handling.
- Uses **Programmed I/O (PIO)**
 - CPU explicitly reads and writes all values to and from registers
 - All data must pass through CPU registers
- Uses **polling**
 - CPU polls device register waiting before send/receive
 - Tight loop!
 - Can't do anything else in the meantime
 - Although could be extended with threads and care...
 - Without CPU polling, no I/O can occur

Recap: Interrupts

- CPU Interrupt-request line triggered by I/O device
- Interrupt handler receives interrupts
- Maskable to ignore or delay some interrupts
- Interrupt vector to dispatch interrupt to correct handler
 - Based on priority
 - Some nonmaskable
- Interrupt mechanism also used for exceptions



Recap: Direct Memory Access

- Avoid **programmed I/O** for lots of data
 - E.g. fast network or disk interfaces
- Requires **DMA controller**
 - Generally built-in these days
- Bypasses CPU to transfer data directly between I/O device and memory
 - Doesn't take up CPU time
 - Can save memory bandwidth
 - Only one interrupt per transfer

I/O Protection

I/O operations can be dangerous to normal system operation!

- Dedicated I/O instructions usually privileged
- I/O performed via system calls
 - Register locations must be protected
- DMA transfers must be carefully checked
 - Bypass memory protection!
 - How can that happen today?
 - Multiple operating systems on the same machine (e.g., virtualized)
 - IOMMUs are beginning to appear...

IOMMUs

IOMMU does the same for the I/O devices as MMU does for the CPU!

- Translates device addresses (so called DVAs) into physical ones
- Uses so called IOTLB (I/O TLB)
- Works for DMA-capable devices :-)

Examples:

- Intel VT-d
- AMD IOMMU
- ...very similar in functionality

Source: Wikipedia

IOMMUs

- Security features for VMs
- Possibility to assign different devices to different address domains
- By address remapping we can isolate the domains from one another, thus 'sandboxing' untrusted devices

Source: Intel VT-d specification

IOMMUs

- IOMMUs were designed for enhancing virtualization
- Remapping & security features can be applied to guest virtual machines
- Better performance than software-based I/O virtualization

Source: Intel VT-d specification

IOMMUs

- IOMMUs take as the 'input request' the ID consisting of:
 - Bus ID, stored in **root tables** (support for multiple buses),
 - Device ID, stored in **context tables** (support for multiple devices within each bus)
 - Function ID, also stored in **context tables** (support for multiple func. within each device)
- Different page table per I/O device

Source: Intel VT-d specification

IOMMUs - Address remapping

- IOMMUs support page remapping
 - Some PCI devices use 32 bit addressing
- IOMMU Page Tables
 - Similar to 'standard' multi-level page tables
 - Write-only / read-only bits
 - Support for huge pages
 - Currently no support for more extended features (e.g., reference bits)

Source: <http://codingresic.geekhold.com/>

IOMMUs

- IOMMUs are much broader topic
- They provide also:
 - Interrupt remapping (you can control interrupts in a similar way as memory accesses)
 - Device I/O TLBs (Intel VT-d)
 - Fault logging
 - ...
- You can think of many interesting use cases for them :-)
- Interested? New ideas?

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Device drivers

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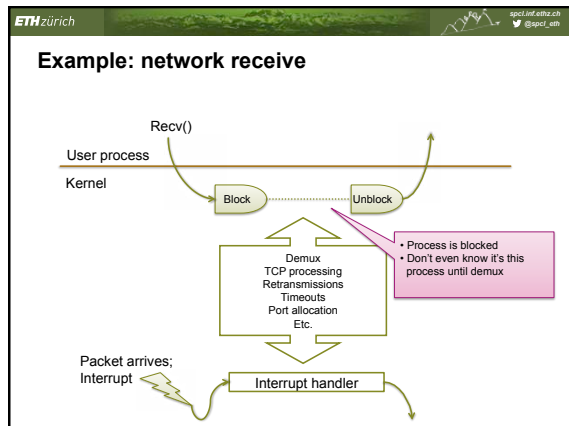
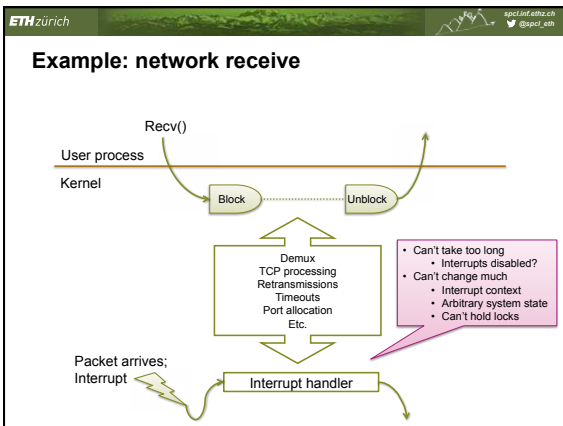
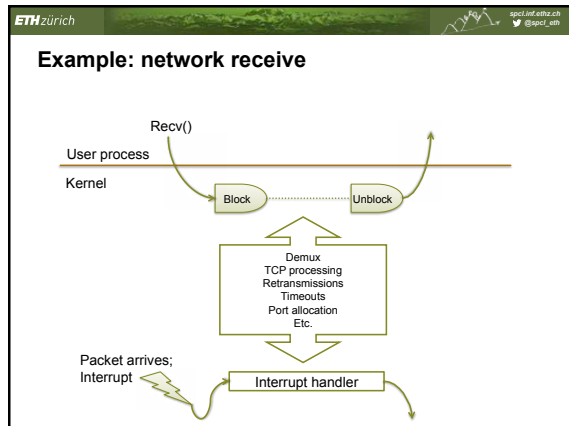
Device drivers

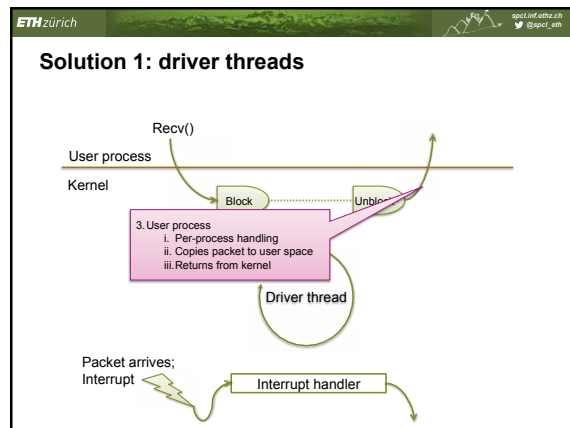
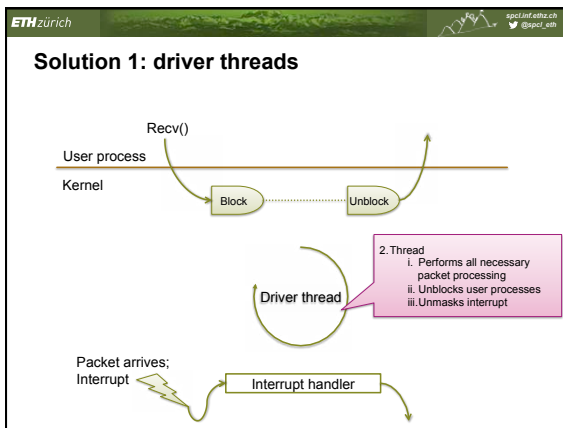
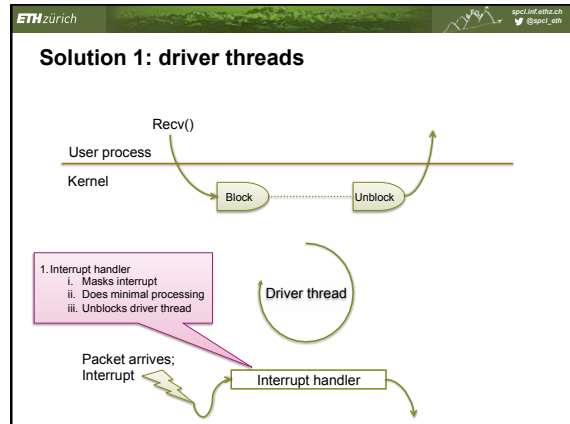
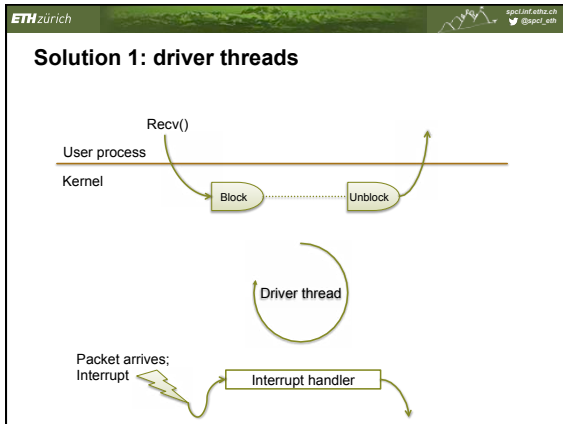
- **Software object (module, object, process, hunk of code) which abstracts a device**
 - Sits between hardware and rest of OS
 - Understands device registers, DMA, interrupts
 - Presents uniform interface to rest of OS
- **Device abstractions ("driver models") vary...**
 - Unix starts with "block" and "character" devices

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Device driver structure: the basic problem

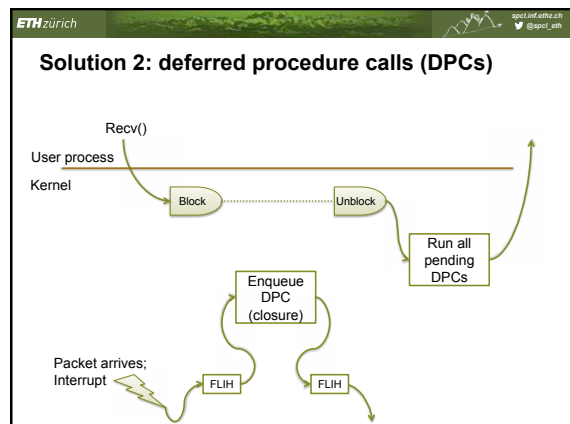
- **Hardware is *interrupt driven*.**
 - System must respond to unpredictable I/O events (or events it is expecting, but doesn't know when)
- **Applications are (often) *blocking***
 - Process is waiting for a specific I/O event to occur
- **Often considerable processing *in between***
 - TCP/IP processing, retries, etc.
 - File system processing, blocks, locking, etc.





Terminology – very confused!

- **1st-level Interrupt Handler (FLIH)**
 - Linux calls this the "top half".
 - In contrast to every other OS on the planet.
- **Thread is an "interrupt handler thread" in Solaris**
 - Other names in other systems... ☺

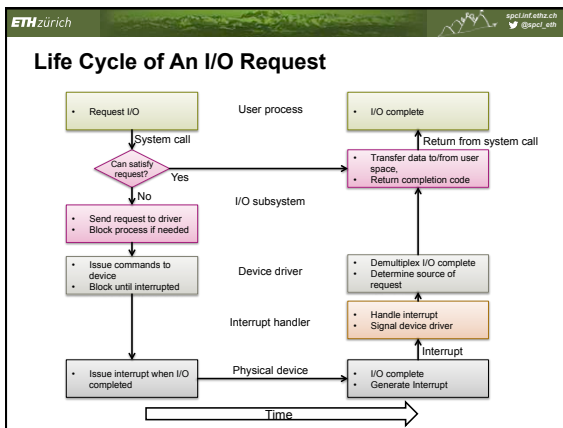


Deferred Procedure Calls

- **Instead of using a thread, execute on the *next* process to be dispatched**
 - Before it leaves the kernel
- **Solution in most versions of Unix**
 - Don't need kernel threads
 - Saves a context switch
 - Can't account processing time to the right process
- **3rd solution: demux early, run in user space**
 - Covered in Advanced OS Course!

More confusing terminology

- **DPCs: also known as:**
 - 2nd-level interrupt handlers
 - Soft interrupt handlers
 - Slow interrupt handlers
 - In Linux ONLY: bottom-half handlers
- **Any non-Linux OS (the way to think about it):**
 - Bottom-half = FLIH + SLIH, called from "below"
 - Top-half = Called from user space (syscalls etc.), "above"





The I/O subsystem

Generic I/O functionality

- **Device drivers essentially move data to and from I/O devices**
 - Abstract hardware
 - Manage asynchrony
- **OS I/O subsystem includes generic functions for dealing with this data**
 - Such as...



The I/O Subsystem

- **Caching - fast memory holding copy of data**
 - Always just a copy
 - Key to performance
- **Spooling - hold output for a device**
 - If device can serve only one request at a time
 - E.g., printing

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The I/O Subsystem

- **Scheduling**
 - Some I/O request ordering via per-device queue
 - Some OSs try fairness
- **Buffering** - store data in memory while transferring between devices or memory
 - To cope with device speed mismatch
 - To cope with device transfer size mismatch
 - To maintain "copy semantics"

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Naming and Discovery

- **What are the devices the OS needs to manage?**
 - Discovery (bus enumeration)
 - Hotplug / unplug events
 - Resource allocation (e.g. PCI BAR programming)
- **How to match driver code to devices?**
 - Driver instance ≠ driver module
 - One driver typically manages many models of device
- **How to name devices inside the kernel?**
- **How to name devices outside the kernel?**

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Matching drivers to devices



- **Devices have unique (model) identifiers**
 - E.g. PCI vendor/device identifiers
- **Drivers recognize particular identifiers**
 - Typically a list...
- **Kernel offers a device to each driver in turn**
 - Driver can "claim" a device it can handle
 - Creates driver instance for it.

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Naming devices in the Unix kernel



(Actually, naming *device driver instances*)

- **Kernel creates identifiers for**
 - Block devices
 - Character devices
 - [*Network devices – see later...*]
- **Major device number:**
 - Class of device (e.g. disk, CD-ROM, keyboard)
- **Minor device number:**
 - Specific device within a class

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Unix Block Devices

- **Used for "structured I/O"**
 - Deal in large "blocks" of data at a time
- **Often look like files (seekable, mappable)**
 - Often use Unix' shared buffer cache
- **Mountable:**
 - File systems implemented above block devices

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Character Devices

- **Used for "unstructured I/O"**
 - Byte-stream interface – no block boundaries
 - Single character or short strings get/put
 - Buffering implemented by libraries
- **Examples:**
 - Keyboards, serial lines, mice
- **Distinction with block devices somewhat arbitrary...**

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Naming devices outside the kernel

- **Device files: special type of *file***
 - Inode encodes <type, major num, minor num>
 - Created with `mknode()` system call
- **Devices are traditionally put in `/dev`**
 - `/dev/sda` – First SCSI/SATA/SAS disk
 - `/dev/sda5` – Fifth partition on the above
 - `/dev/cdrom0` – First DVD-ROM drive
 - `/dev/ttyS1` – Second UART

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Pseudo-devices in Unix

- **Devices with no hardware!**
- **Still have major/minor device numbers. Examples:**

```

/dev/stdin
/dev/kmem
/dev/random
/dev/null
/dev/loop0

```

etc.

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Old-style Unix device configuration

- **All drivers compiled into the kernel**
- **Each driver probes for any supported devices**
- **System administrator populates `/dev`**
 - Manually types `mknode` when a new device is purchased!
- **Pseudo devices similarly hard-wired in kernel**

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Linux device configuration today

- **Physical hardware configuration readable from `/sys`**
 - Special fake file system: `sysfs`
 - Plug events delivered by a special socket
- **Drivers dynamically loaded as kernel modules**
 - Initial list given at boot time
 - User-space daemon can load more if required
- **`/dev` populated dynamically by `udev`**
 - User-space daemon which polls `/sys`

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Next time:

- **Network stack implementation**
- **Network devices and network I/O**
- **Buffering**
- **Memory management in the I/O subsystem**