

Little's Law (1961)

Example 1: In a Starbucks, on average

- every minute 2 customers enter and leave
 - every customer spends 8 minutes in the store
- How many people are inside? $16 = 2 \times 8$

Example 2: In your wine cellar, on average

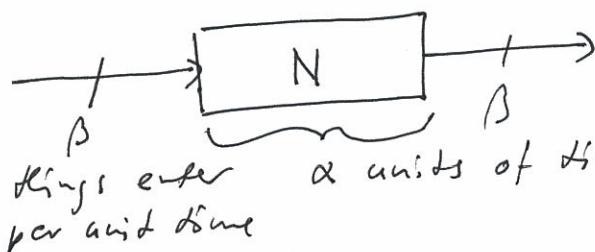
- there are 600 bottles

- you drink and buy 50/year

How long is every bottle in the cellar? $12 = 600/50$

Little's Law: Given a stable (arrival rate =
departure rate) system

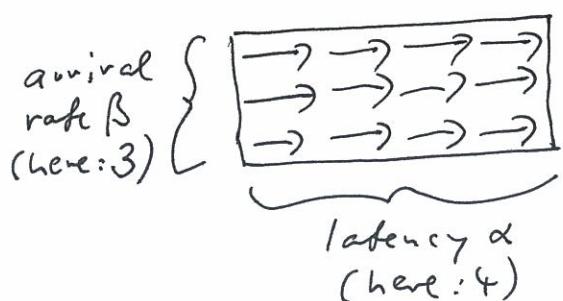
$$N = \text{# things in system}$$



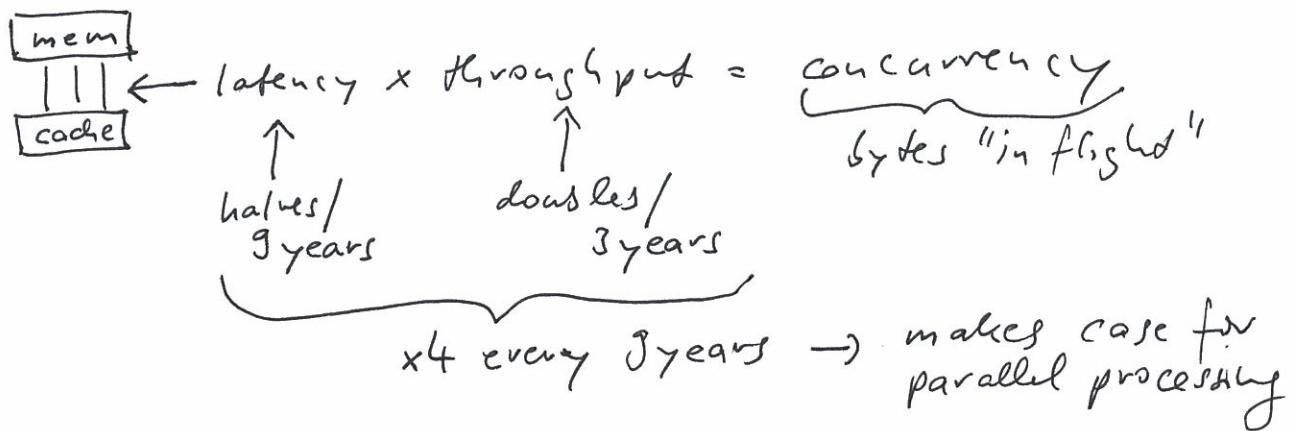
$$\text{Then: } N = \alpha \beta$$

Seems trivial, but the interesting aspect is the independence of input/output distribution.

useful visualization:



Example: Memory system



$$\text{Core 2: } \beta = 2 \text{ B/cycle}$$

$$\alpha \approx 100 \text{ B/cycle}$$

$$\Rightarrow N = 200 \beta = 50 \text{ floats or ints}$$

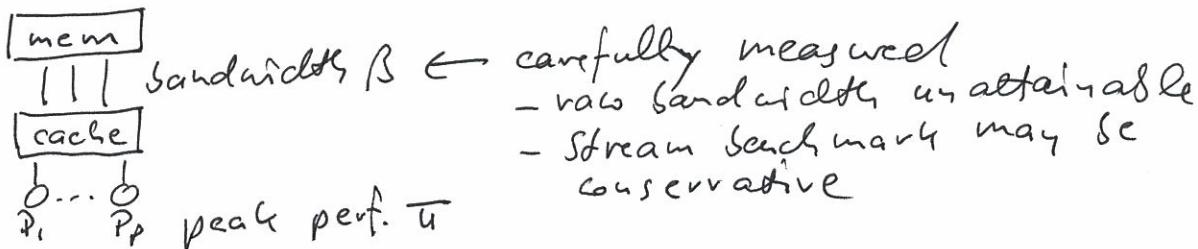
Performance Bounds: Roof Line model

(Williams et al. 2008)

Which resources in a microarchitecture bound performance?

- peak performance [ops/cycle]
- memory bandwidth [bytes/cycle]
- <other>

Platform model:



Algorithm/program model:

$$\text{operational intensity} = \frac{W}{Q} = \frac{\# \text{ ops}}{\# \text{ bytes transferred}_{\text{mem} \leftrightarrow \text{cache}}} \left[\frac{\text{ops}}{\text{byte}} \right]$$

"ops" could be

- floating point ops (adds/mults) for numerical code
- comparisons (for sorting)
- <other>

W: derive on paper or
instrument your code or
perf. counters

Q: perf. counters

[roofline model assumes cold cache]

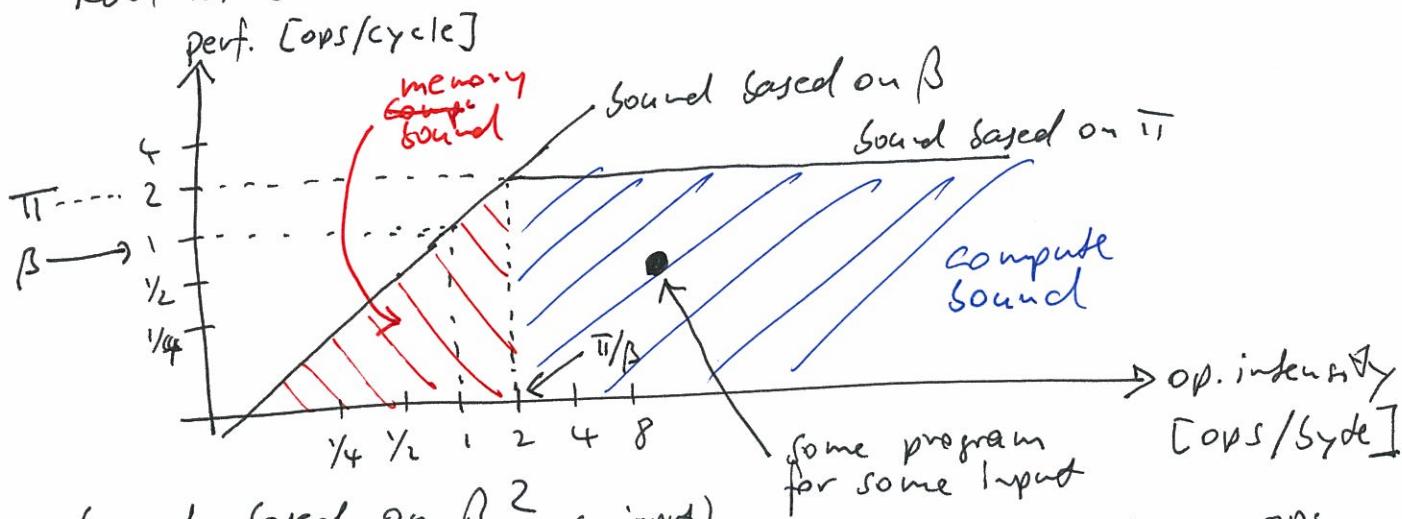
For some functions, asymptotic results on optimal op. intensity are available.

Assume cache size of m bytes. Then the optimal $W/Q = W/Qm$ is

$$\text{FFT/sortby: } \Theta(\log m) \quad (\text{m-way merge sort})$$

$$\text{Matrix mult.: } \Theta(\sqrt{m}) \quad (\text{widely blocked})$$

Roofline model: (example $\pi=2, \beta=1$)



bound based on β^2 (cont'd)

- assume program has op. intensity of $\times \frac{\text{ops}}{\text{byte}}$

- the program gets at most $\beta \frac{\text{bytes}}{\text{cycle}}$

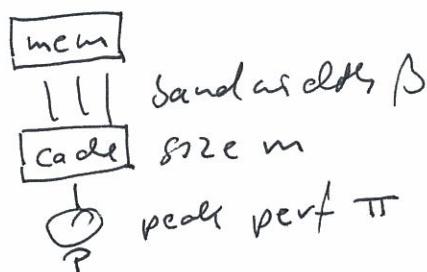
$$\Rightarrow \text{perf} = \gamma \leq \beta \cdot x$$

$$\Leftrightarrow \log_2(\gamma) \leq \log_2(x) + \log_2(\beta) \quad (\text{slope is } 1)$$

$$x=1 \Rightarrow \gamma \leq \beta$$

Balance principles I (Kung 86)

platform model:



algorithm model:

Q_m : data transfer
mem \leftrightarrow code

W : work = #ops

The processor is called balanced for an algorithm (on an input) if compute time = data transfer time, i.e., assuming perfect utilization:

$$\frac{W}{\pi} = \frac{Q_m}{\beta} \Leftrightarrow \frac{\pi}{\beta} = \frac{W}{Q_m} \quad (\text{compare to roofline model!})$$

If π is increased by α , β can also be increased "times" to rebalance. But π grows faster than β !

Hence this question: If $\pi \rightarrow a\pi$, how much to increase m to rebalance?

Consider algorithms with optimal $\frac{W}{Q_m}$

Case 1: Matrix mult.

$$\frac{W}{Q_m} = \Theta(\sqrt{m})$$

$$\Rightarrow \frac{\pi}{\beta} \text{ increased } \times \alpha \rightarrow m \text{ needs increase } \times \alpha^2$$

Case 2: FFT / sorting

$$\frac{W}{Q_m} = \Theta(\log m)$$

$$\Rightarrow \frac{\pi}{\beta} \text{ increased } \times \alpha \rightarrow m \text{ needs increase } \propto m^\alpha$$

Both are unrealistic.

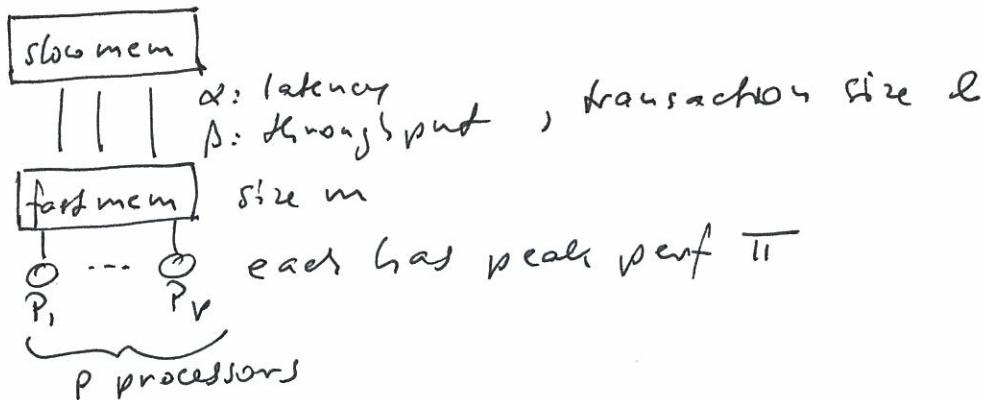
Balance principles II (Czerniowski et al. 2011)

Goal: More detailed balance principles for multicores

Applications:

- relationship between hardware and algorithm parameters
- reasoning about architecture tradeoffs

Platform model:



Algorithm model:

PRAT: $W(n), \delta(n)$

Memory transfers of size ℓ : $Q_{m,e}(n)$

Assumptions:

- optimal $W(n)$
- optimal $W(n)/Q_{m,e}(n)$

Question: How to get $Q_{p,m,e}(n)$ (i.e., for r processors)

Answer:

- there are general bounds based on $Q_{m,e}(n)$ and a given scheduler
- some direct results are available

~~A~~ Processor is balanced for algorithm if

$$T_{mem} \leq T_{comp} \quad (\text{Kung used } "=")$$

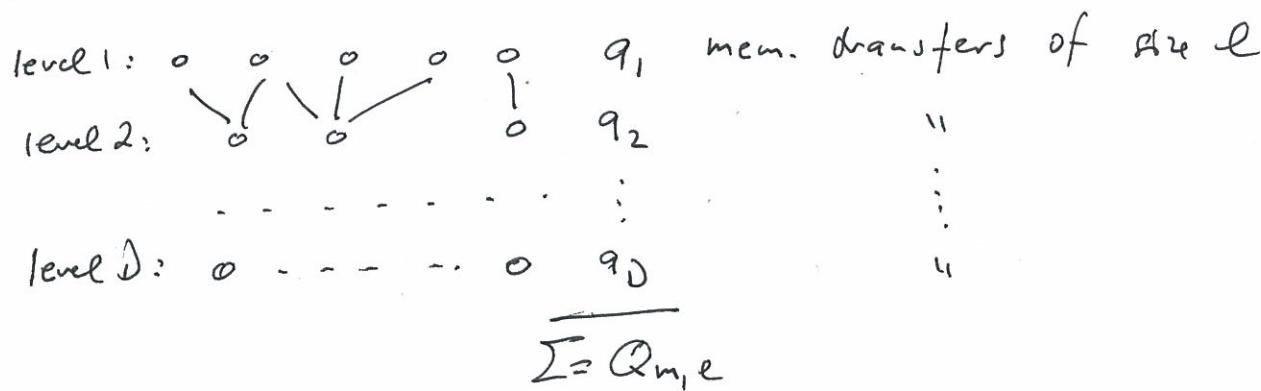
This is equivalent to "compute-bound".

Kung would get:

$$\frac{Q \cdot \ell}{\beta} \leq \frac{W}{r \bar{\pi}} \iff \frac{r \bar{\pi}}{\beta} \leq \frac{W}{Q \cdot \ell}$$

Estimating T_{mem} :

Idea: divide DAG into levels



In each level use $\alpha\beta$ model: $\alpha + \frac{q_i \cdot l}{\beta}$

$$\Rightarrow T_{mem} \approx \sum_{i=1}^D \left(\alpha + \frac{q_i \cdot l}{\beta} \right) = \alpha D(n) + \frac{Q_{prim,e}(n)}{\beta}$$

Estimating T_{comp} : Bresen's theorem

$$T_{comp} \approx (D + \frac{W}{P}) \cdot \frac{1}{n} = (D(n) + \frac{W(n)}{P}) \frac{1}{n}$$

Balance principle: $T_{mem} \leq T_{comp}$

$$\Leftrightarrow \frac{Pn}{\beta} \left(1 + \frac{\alpha\beta/l}{Q/D} \right) \leq \frac{W}{Q \cdot l} \left(1 + \frac{P}{W/D} \right)$$

Kung

↖ ↘

mem. parallelism of algorithm comp. parallelism of algorithm

Example: Matrix mult.

$$Q \geq \frac{W}{\sqrt{2} \cdot \epsilon \sqrt{m/p}}$$

(Irony et al. 2004)

$$\Rightarrow \text{Balance principle } \frac{Pn}{\beta} \leq \sqrt{\frac{W}{P}}$$

Doubling P requires doubling both β and m
or $m \rightarrow 8m$ to resalance

Note: doubling P is very different than doubling n
(even though both double peak perf.)

Other example: Comparison-based sorting (+ work steady)

$$\frac{Pn}{\beta} \leq O(\log \frac{m}{P})$$